

# Next Generation of Reference Point Determinations

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1. Motivation
2. Determination model for a radio telescope
3. Effects of errors on reference point determination
4. Automated reference point monitoring
5. Results of reference point monitoring
6. Conclusions and outlook

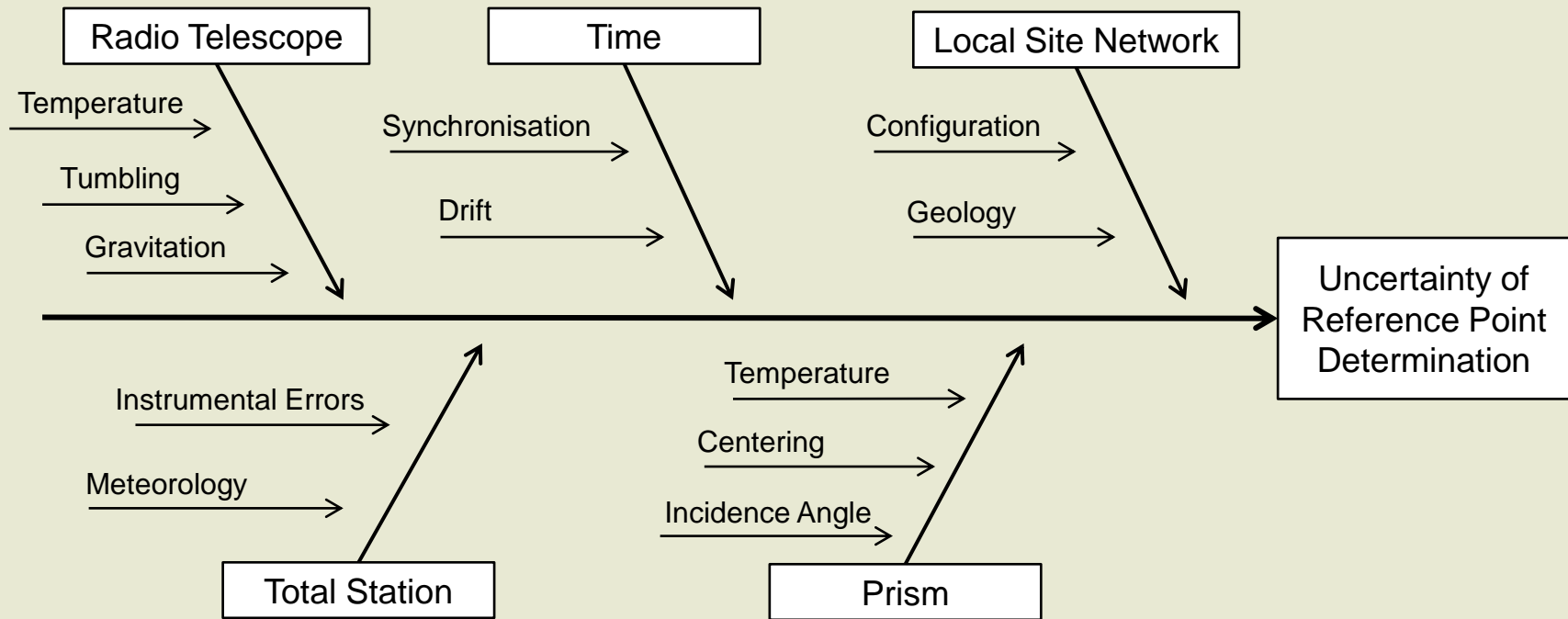
- Geodetic co-location stations
  - Crucial for the International Terrestrial Reference Frame
  - Essential for a meaningful combination of the different space geodetic techniques (→ local tie vectors)
- Goal
  - Ensuring an utmost level of accuracy of local tie vectors
  - Both in the spatial and temporal domain
  - Reducing time-consuming field work
- Automated reference point determination
  - Agenda VLBI2010
  - Global Geodetic Observation System (GGOS)

Mathematical model emulates trajectory of the point  $\mathbf{P}_{\text{Tel}} = [b \ a \ 0]^T$  and regards imperfection

$$\mathbf{P}_{\text{Obs}} = \mathbf{P}_{\text{RP}} + \mathbf{R}_{\theta}^x \mathbf{R}_{\phi}^y \mathbf{R}_{\alpha-O_{\alpha}}^z \mathbf{R}_{\psi}^y (\mathbf{E}_{\text{CC}} + \mathbf{R}_{\varepsilon-O_{\varepsilon}}^z \mathbf{P}_{\text{Tel}})$$

$\mathbf{P}_{\text{RP}}$	IVS-defined reference point
$\mathbf{E}_{\text{CC}}$	axis-offset
$\psi$	inclination angle (azimuth to elevation axis)
$\theta$ and $\phi$	vertical misalignment (telescope system – local network)
$O_{\alpha}$ and $O_{\varepsilon}$	orientation angles
$\mathbf{R}_{\theta}^x, \mathbf{R}_{\phi}^y, \dots$	Rotation matrices

## Ishikawa diagram to visualise error budgeting



## Compensations for each observed position

- Height compensation by recorded invar data
- Thermal expansion of the telescope structure using monument temperature

$$a_{\Delta T_i} = a(1 + \gamma_S \Delta T_i)$$

$$b_{\Delta T_i} = b(1 + \gamma_S \Delta T_i)$$

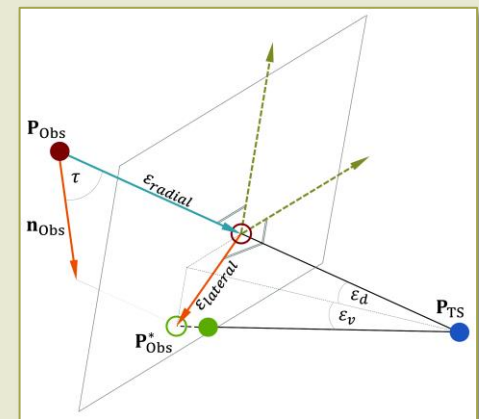
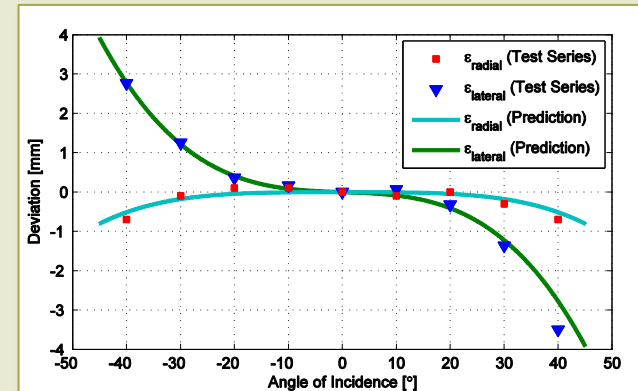
$$Z_{P_{RP}, \Delta T_i} = Z_{P_{RP}} + (\gamma_F h_F + \gamma_S h_S) \Delta T_i$$

- Calibration parameters or 2-face measurements
- Meteorological correction of EDM
- Error of reflector alignment

- Optical shift of the prism center
- Causes lateral and radial deviations
- Depending on angle of incidence
- Not correctable by two-face observations
- Test set-up
  - High precision total station TS30
  - Automatic target recognition (ATR)
  - Standard GPR121-type prism (identical in construction with GPH1P)
  - $10^\circ$ -increments of angle of incidence



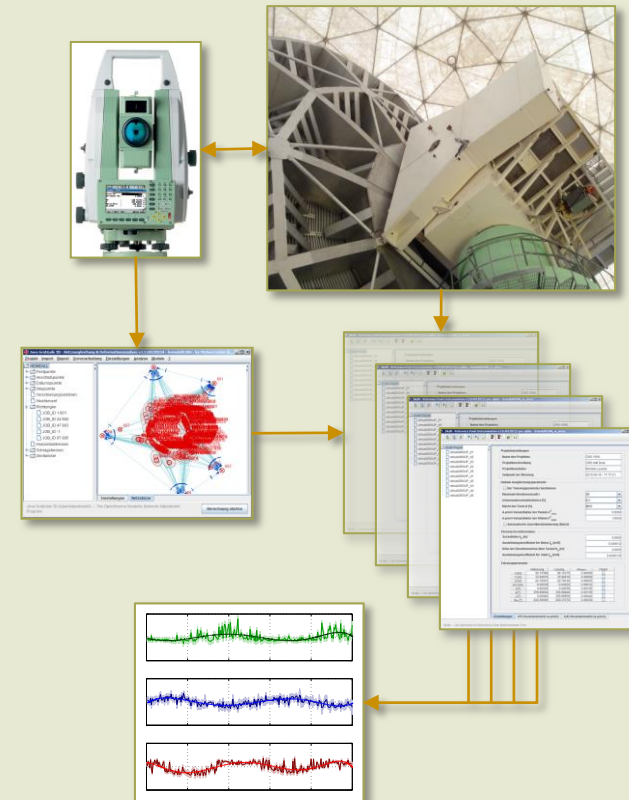
- Significant deviations
  - E.g. at angle of incidence of  $35^\circ$ 
    - 1.2 mm lateral
    - 0.2 mm radial
- Angle of incidence depends on
  - Alignment of the prism (general)
  - Elevation and azimuth angles  
(in framework of RP determination)
- Separating into horizontal and vertical correction values



Lösler et al. (2013), JGeod; DOI: 10.1007/s00190-013-0647-y

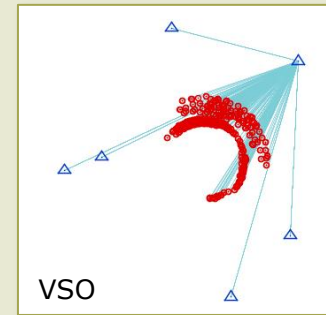
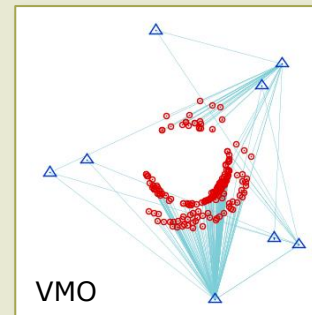
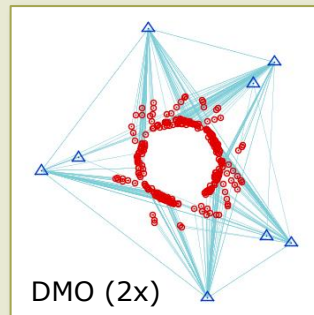
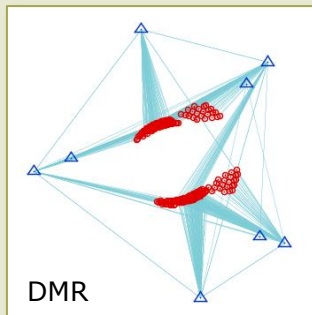


- Central data management
  - HEIMDALL system
  - Interfaces for data transfer
  - SQL-based DBMS
- Monitoring modules
  - Communication with peripheral devices
  - Observation plan (based on VLBI-schedule)
  - Spatial network adjustment
  - Reference point determination
  - Time series analysis



- Field experiments at Onsala, testing different observation configurations

Approaches/Experiments	I	II	III	IV	V
<u>D</u> edicated survey/Real <u>V</u> LBI schedule	D	D	V	D	V
<u>S</u> ingle/ <u>M</u> ultiple survey stand point(s)	M	M	M	M	S
Target was observed <u>O</u> nce/ <u>R</u> edundantly	R	O	O	O	O



- Considering each single solution as an independent realisation of a random experiment
- Recursive parameter estimation
  - Combination incorporates information of prior results
  - Using full variance-covariance-matrix of single solution
  - Regarding timeliness of data via additional variance matrix of the process noise
  - Model expansion is possible (e.g. for seasonal variation)
- $\hat{\mathbf{x}}_j = \hat{\mathbf{x}}_{j-1} + \mathbf{K}_{j-1,j}(\mathbf{x}_j - \hat{\mathbf{x}}_{j-1})$  and

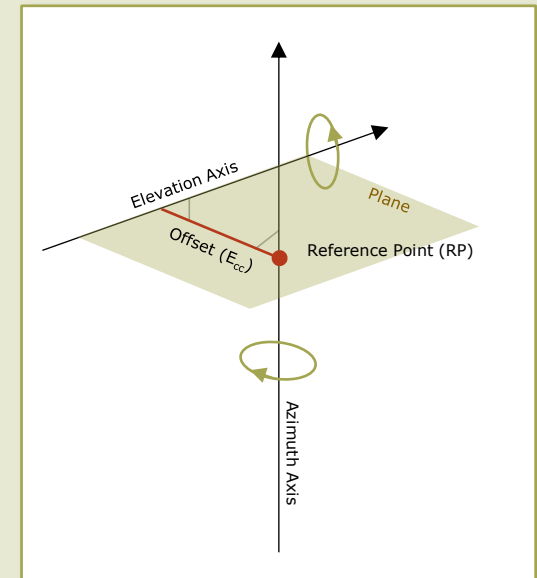
$$\mathbf{Q}_{\hat{\mathbf{x}}_j \hat{\mathbf{x}}_j} = \mathbf{Q}_{\hat{\mathbf{x}}_{j-1} \hat{\mathbf{x}}_{j-1}} - \mathbf{K}_{j-1,j} \mathbf{Q}_{\hat{\mathbf{x}}_{j-1} \hat{\mathbf{x}}_{j-1}}$$

$$\text{where } \mathbf{K}_{j-1,j} = \mathbf{Q}_{\hat{\mathbf{x}}_{j-1} \hat{\mathbf{x}}_{j-1}} \left( \mathbf{Q}_{\mathbf{x}_j \mathbf{x}_j}^{\Delta t} + \mathbf{Q}_{\hat{\mathbf{x}}_{j-1} \hat{\mathbf{x}}_{j-1}} \right)^{-1}$$

$$\mathbf{Q}_{\mathbf{x}_j \mathbf{x}_j}^{\Delta t} = \mathbf{Q}_{\mathbf{x}_j \mathbf{x}_j} + \mathbf{B} \mathbf{C}_{nn} \mathbf{B}^T$$

- Filtered combination of single experiments

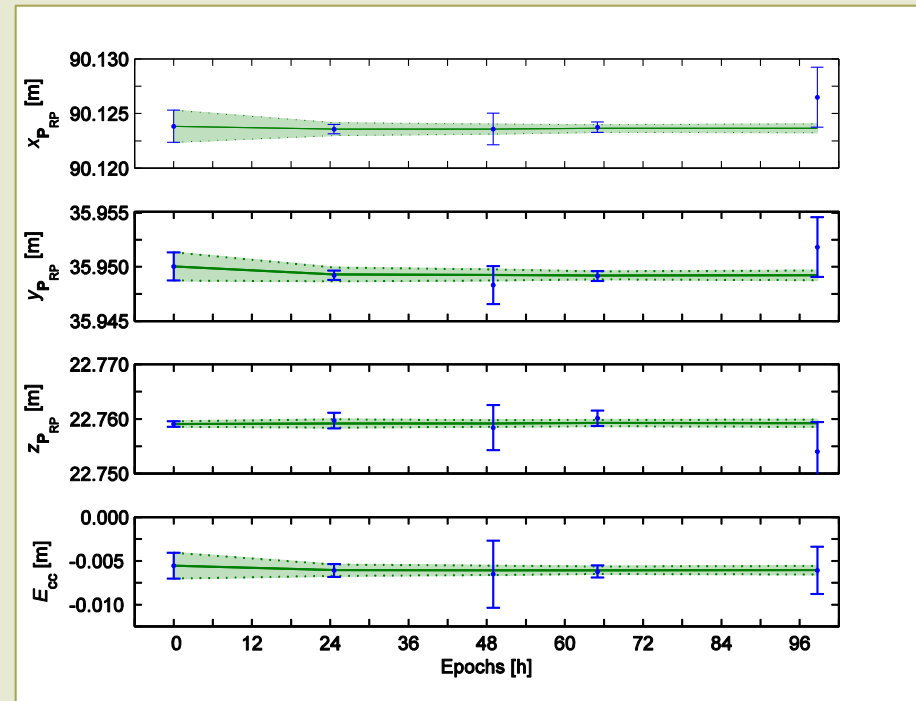
	I+II	I+II+III	I+...+IV	I+...+V
$X_{RP}$ [m]	90.1236 $\pm 0.0002$	90.1236 $\pm 0.0001$	90.1236 $\pm 0.0001$	90.1236 $\pm 0.0001$
$Y_{RP}$ [m]	35.9493 $\pm 0.0002$	35.9492 $\pm 0.0002$	35.9492 $\pm 0.0001$	35.9492 $\pm 0.0001$
$Z_{RP}$ [m]	22.7592 $\pm 0.0002$	22.7592 $\pm 0.0002$	22.7593 $\pm 0.0002$	22.7592 $\pm 0.0002$
$E_{CC}$ [m]	-0.0061 $\pm 0.0002$	-0.0061 $\pm 0.0002$	-0.0061 $\pm 0.0001$	-0.0060 $\pm 0.0001$



- Filtered combination of single experiments

	I+II	I+II+III	I+...+IV	I+...+V
$X_{RP}$ [m]	90.1236 $\pm 0.0002$	90.1236 $\pm 0.0001$	90.1236 $\pm 0.0001$	90.1236 $\pm 0.0001$
$Y_{RP}$ [m]	35.9493 $\pm 0.0002$	35.9492 $\pm 0.0002$	35.9492 $\pm 0.0001$	35.9492 $\pm 0.0001$
$Z_{RP}$ [m]	22.7592 $\pm 0.0002$	22.7592 $\pm 0.0002$	22.7593 $\pm 0.0002$	22.7592 $\pm 0.0002$
$E_{CC}$ [m]	-0.0061 $\pm 0.0002$	-0.0061 $\pm 0.0002$	-0.0061 $\pm 0.0001$	-0.0060 $\pm 0.0001$

- Single solution with  $3\sigma$  error bars (blue)
- Combined solution with  $3\sigma$  error band (green)



- General
  - Neglecting the reflector alignment error yields significant systematic errors
  - Temperature compensation for each observed point
- At Onsala: Five reference point determinations campaigns in **one** week
  - Dedicated reference point determinations
  - Collateral reference point determination during regular VLBI schedule
  - No station downtime during local survey
  - Achieved sub-mm accuracy for reference point and eccentricity offset

- Automated monitoring system HEIMDALL fulfills the extended requirements of VLBI2010 and GGOS
- Recursive parameter estimation
  - Combination incorporates information of prior results
  - Increasing reliability
- Outlook
  - Plan to implement the automated monitoring system for the Onsala Twin Telescope project
  - Extension to further co-located equipment to achieve complete automated local-tie surveys

Thank you for your attention!